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24. CHAPTER 2. E2.4. Mathematical Models of Systems. Since  $R(s) = 1/s$ , we have  $Y(s) = 6(s + 50) / (s(s + 30)(s + 10))$ . The partial fraction expansion of  $Y(s)$  is given by  $Y(s) = A_1/s + A_2/(s + 30) + A_3/(s + 10)$ .

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For mass 1 and 2 we have  $M_1 \ddot{x}_1 + k_1 x_1 + k(x_1 - x_2) = F(t)$   
 $M_2 \ddot{x}_2 + k(x_2 - x_1) + b \dot{x}_2 = 0$ . Using a force-current analogy, the analogous electric circuit is shown in Figure P2.3, where  $C = 1/k$ ,  $L = 1/b$ . Solutions Manual to Accompany Modern Control Systems, Eleventh Edition, by Richard C Dorf and Robert H. Bishop.

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(b) The closed-loop system is a second-order system with natural frequency  $\omega_n = 110$  , 166 Solutions Manual to Accompany Modern Control Systems, Eleventh Edition, by Richard C Dorf and Robert H. Bishop.

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